Widelane Ambiguity Resolution Between Different Receiver Types

- It is now apparent that—in addition to P1/P2 and C1/P2' receivers—a third receiver class must be recognized: C1/P2 receivers
- Known receivers of this type are: Leica SR9600, Leica CRS1000, Novatel OEM4, Trimble MS750, Trimble 4700, Trimble 5700. A corresponding receiver table is maintained and regularly posted to: http://www.aiub. unibe.ch/download/BSWUSER/GEN/RECEIVER.
- types for widelane ambiguity resolution, or precise clock estimation. Updated P1–C1 bias values are accessible, e.g., at: http://www.aiub. unibe.ch/download/CODE/P1C1.F when making use of code measurements coming from different receiver The consideration of P1–C1 differential code bias (DCB) values is a must

Widelane Ambiguity Resolution Between Different Receiver Types (Continued)

- P1–C1 bias values and to make given code measurements consistent to P1/P2 data, respectively. The CC2NONCC program is available at: ftp://The RINEX conversion utility, CC2NONCC, is an easy-to-use tool to correct igscb.jpl.nasa.gov/igscb/software/cc2noncc/cc2noncc.f
- The following corrections are made:
- P1/P2: No correction
- C1/P2': C1 + (P1 C1) = P1 and P2' + (P1 C1) = P2
- C1/P2: C1 + (P1 C1) = P1

Note that P2' stands for the linear combination C1 + (P2 - P1).

How to Use P1–P2 and P1–C1 Satellite DCB Information

observable types: most important linear combinations derived from various combinations of code The following table gives the corrections due to satellite-specific DCBs for the

91	L5	L4	L3	L2	<u> </u>	C
0	$-1.98 \cdot B_{P1-P2}$	$-B_{P1-P2}$	0	$+2.55 \cdot B_{P1-P2}$	$+1.55 \cdot B_{P1-P2}$	P1/P2
	$-1.98 \cdot B_{P1-P2}$	$-B_{P1-P2}$		$+2.55 \cdot B_{P1-P2}$	$+1.55 \cdot B_{P1-P2}$	C1/P2'
$-B_{P1-C1}$	$+B_{P1-C1}$		$+B_{P1-C1}$	$+B_{P1-C1}$	$+B_{P1-C1}$	
	$-1.98 \cdot B_{P1-P2}$	$-B_{P1-P2}$		$+2.55 \cdot B_{P1-P2}$	$+1.55 \cdot B_{P1-P2}$	C1,
$-0.56 \cdot B_{P1-C1}$	$+4.53 \cdot B_{P1-C1}$	$+B_{P1-C1}$	$+2.55 \cdot B_{P1-C1}$		$+B_{P1-C1}$	C1/P2

"Melbourne-Wübbena" LC, respectively (following the notation used in the Bernese L3, L4, L5, and L6 denote the ionosphere-free, geometry-free, wide-lane, and GPS Software).

0.562, where ν_1 and ν_2 are the basic carrier frequencies 2.546, $\nu_1 \nu_2/(\nu_1^2 - \nu_2^2) = 1.984$, $\nu_1/(\nu_1 - \nu_2) = 4.529$, and $\nu_1/(\nu_1 + \nu_2)$ The factors involved are computed as $\nu_2^2/(\nu_1^2 - \nu_2^2) = 1.546$, $\nu_1^2/(\nu_1^2 - \nu_2^2)$