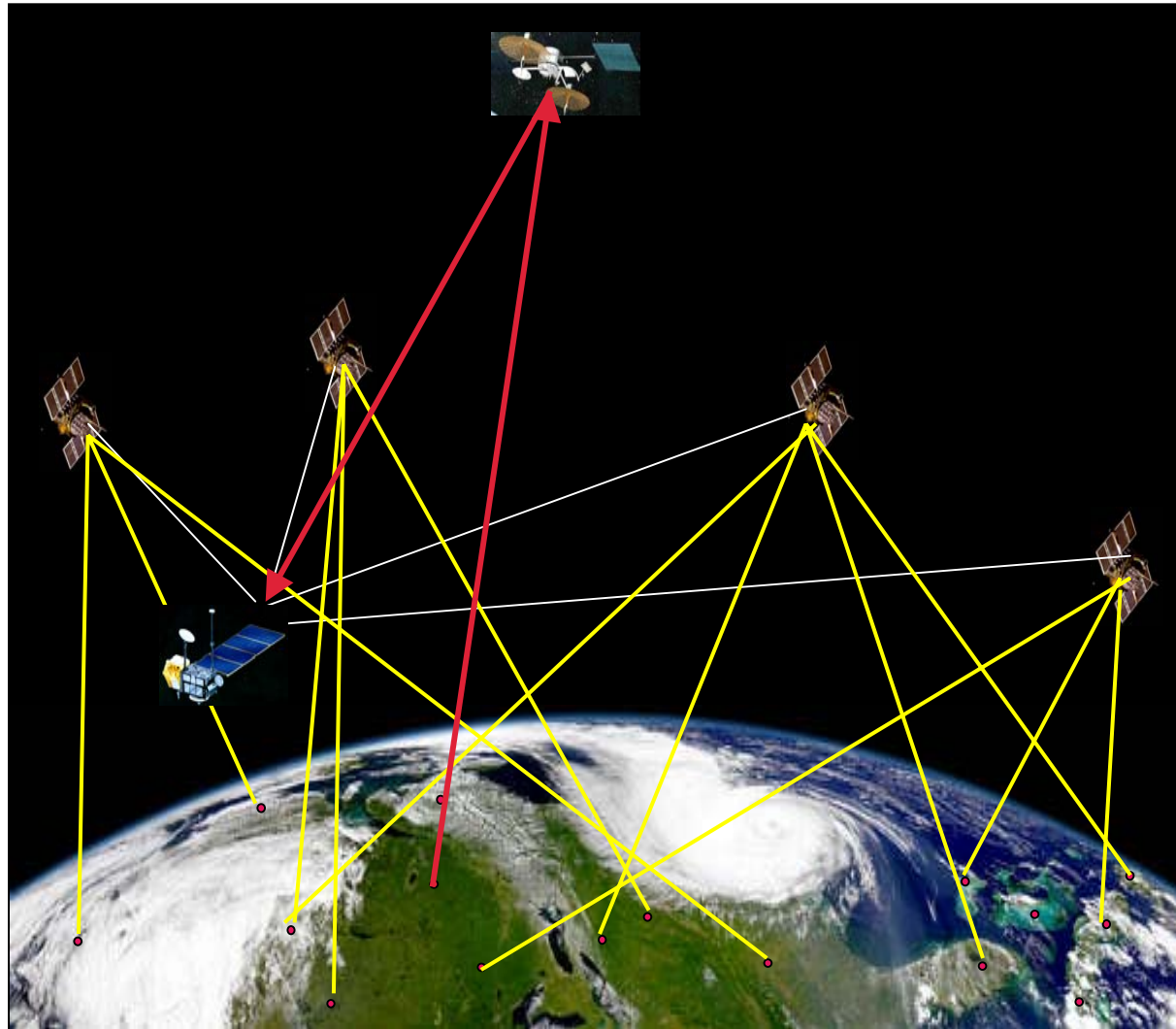


Real-Time Aspects, the JPL Perspective





Global Differential GPS





History of Differential GPS at JPL

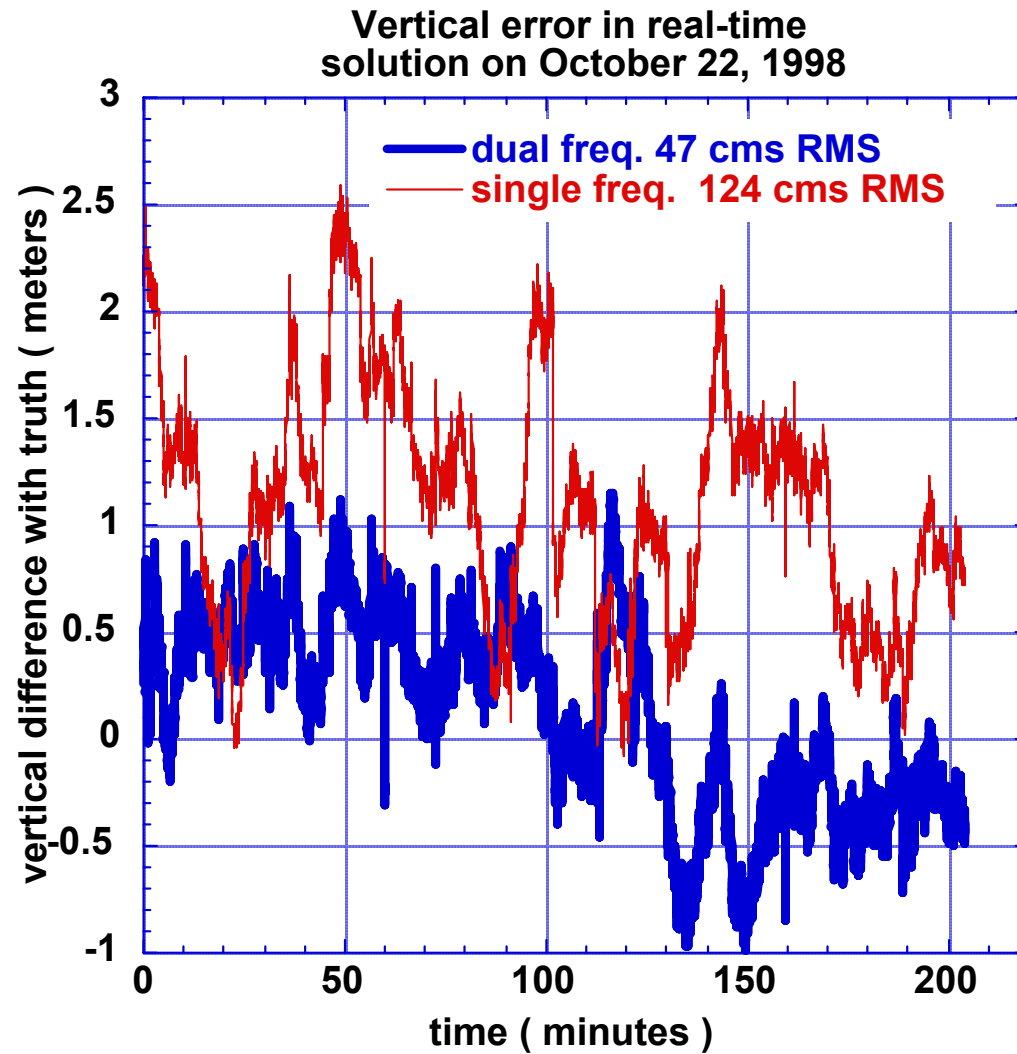


- **1995 white paper on WADGPS (Tom Yunck, et al.)**
 - “A Prototype WADGPS System for Real Time Sub-Meter Positioning Worldwide,” Proceedings of ION GPS 96, Kansas City, Kansas, September, 1996.
- **1996 provide core s/w for Satloc’s WADGPS**
 - Selected as prototype for FAA’s WAAS (US)
 - Software licensed by Raytheon

**Demonstrated 30-40 cms rms.
horizontal and sub 50 cms rms.
vertical accuracy**



DC-8 AirSAR Flight Tests





An Internet-Based Global Differential GPS System, Initial Results

- Real-Time Data
 - 15 Global Stations
- Dual-Freq. User Positions, Anywhere (Internet)
 - Horizontal < **10** cm bias, Sigma < **5** cm
 - Vertical < **20** cm bias, Sigma < **10** cm



... and 4 years later



- **Continue to refine techniques and algorithms**
 - Earth radiation model in real-time orbit determination
 - 6 different solar pressure models
 - Adaptive weighting to control long-term clock biases
 - Two-stage filter implementation for PPP end user

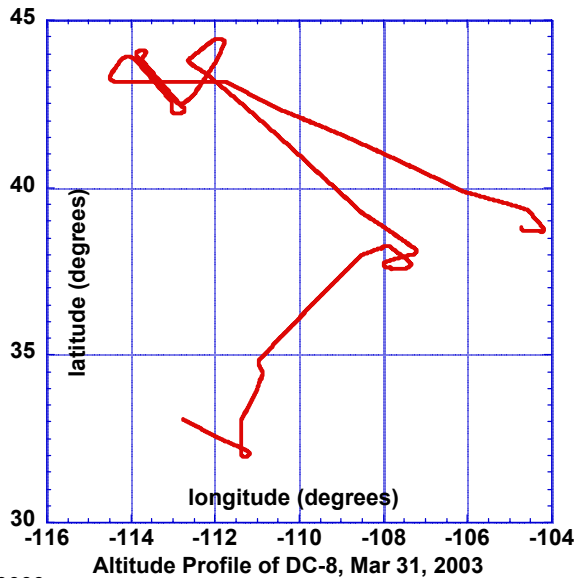
- **Improve on robustness of the network and infrastructure**
 - Two independent operation centers with redundant computer infrastructures
 - Dual pathways for raw observables



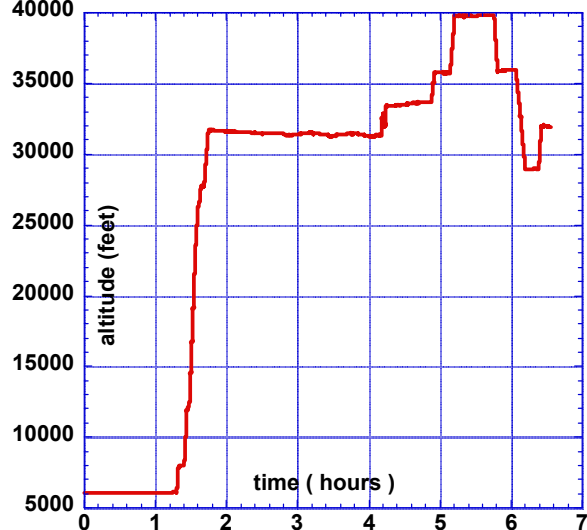
DC-8, Colorado Springs, CO to EAFB, CA



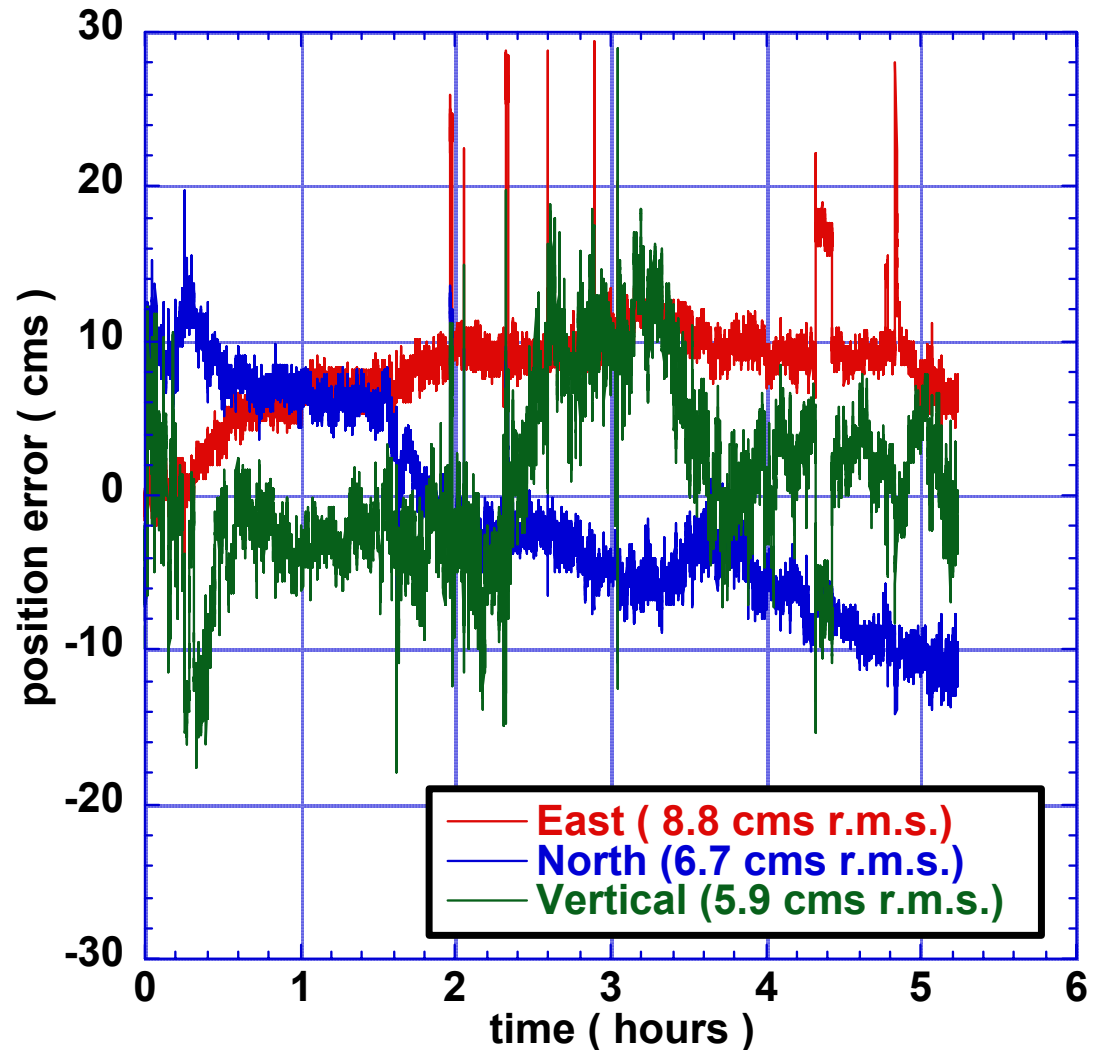
Flight Path of DC-8, Mar 31, 2003



Altitude Profile of DC-8, Mar 31, 2003



Real-Time Position Error of DC-8, Mar 31, 2003





NASA's Global Differential GPS System



GDGPS Operations Center

TDRS



Terrestrial and airborne users

Internet
←
Iridium
Inmarsat

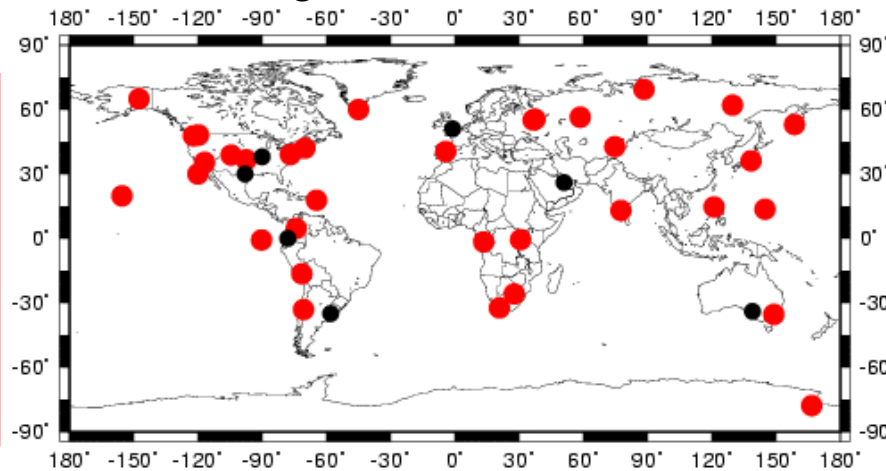


Uplink
→



Internet
↑

NASA's global real time network



Broadcast
↓



Space users

**Developed under the
NASA Advanced
Information Systems
Technology Program**

**For more information see:
<http://galia.jpl.nasa.gov/igdg>**



GDGPS Correction Latency Monitor



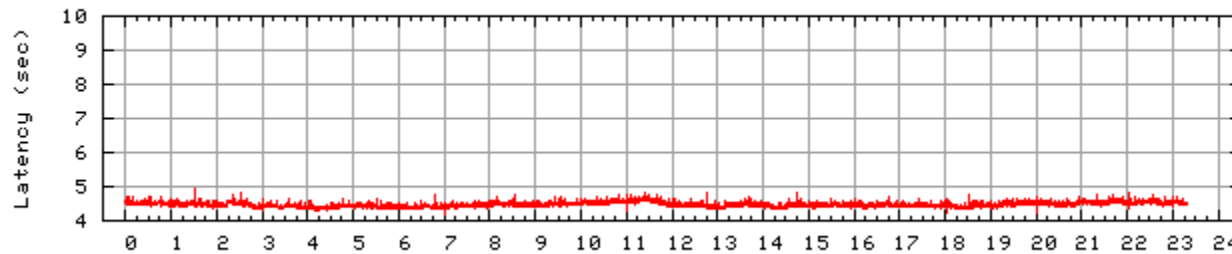
JPL RTG GDGPS Correction Message Latency: **gmon11a**

Last run: Fri Jan 23 16:17:00 2004 (UTC)

4-sec Latency Monitor host=fast11a (15-days):

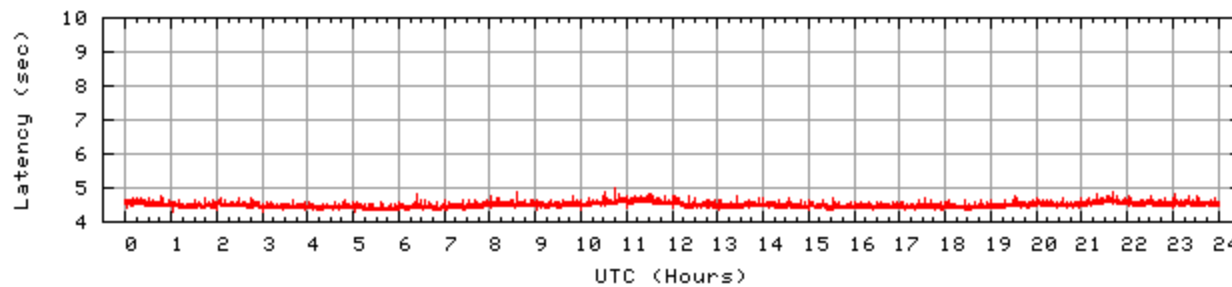
Day 1:

Run[UTC]: Mon Mar 22 23:17:00 2004; Latency on fast11a for Mon Mar 22 00:00:00 2004



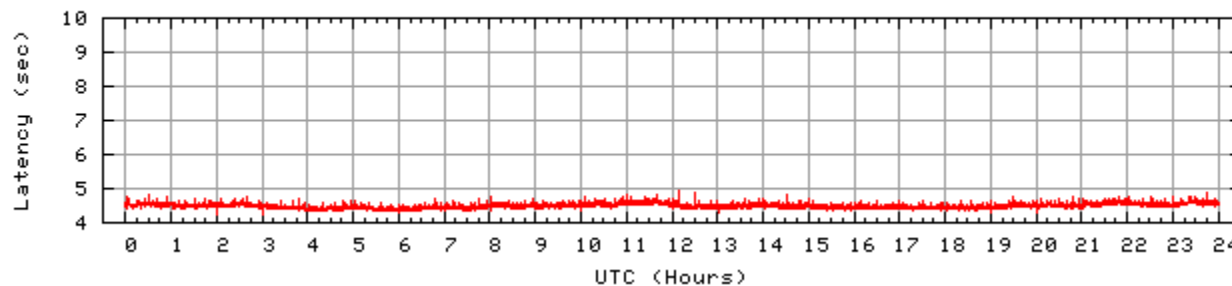
Day 2:

Run[UTC]: Mon Mar 22 23:17:00 2004; Latency on fast11a for Sun Mar 21 00:00:00 2004



Day 3:

Run[UTC]: Mon Mar 22 23:17:00 2004; Latency on fast11a for Sat Mar 20 00:00:00 2004

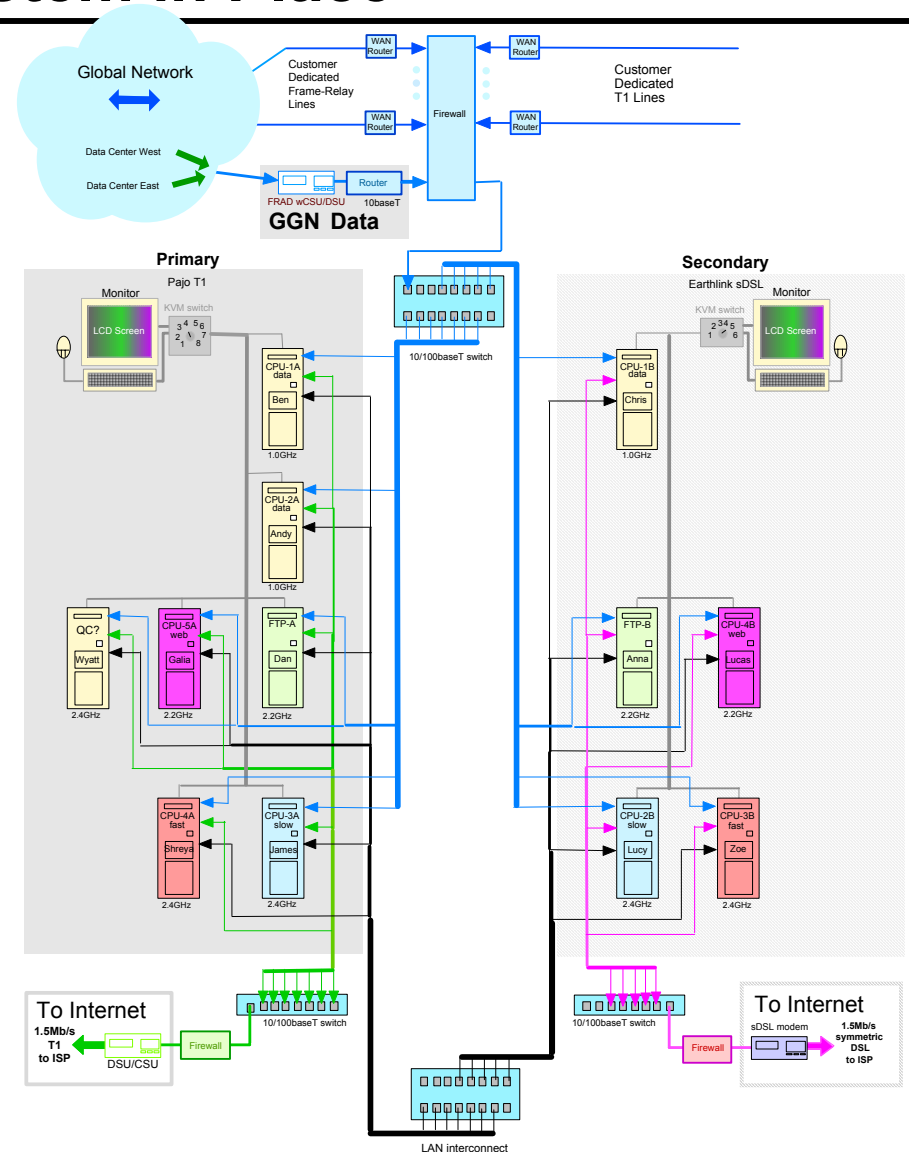




Mature and Reliable Ground Operations System in Place



- Reliability through redundancy
 - No single points of failure
 - Dual data stream accumulators
 - Numerous reference sites
 - 66 and growing
 - Multiple reference clocks
 - USNO & AMC
 - Redundant correction processes
- Automatic (unmanned operations)
 - fault detection
 - data rerouting
- Integrity monitoring
- Web monitoring in the public domain
- **99.99% reliability since 2000**



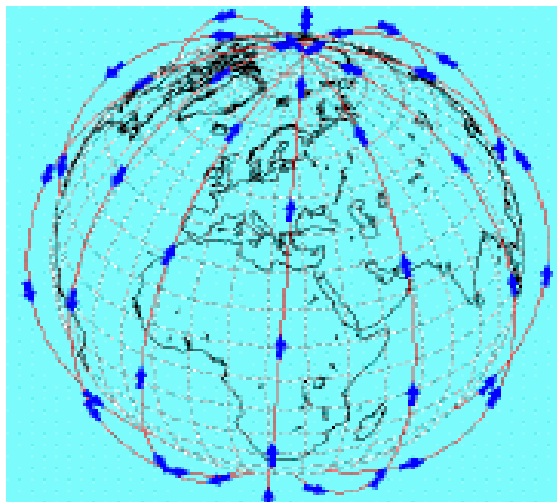
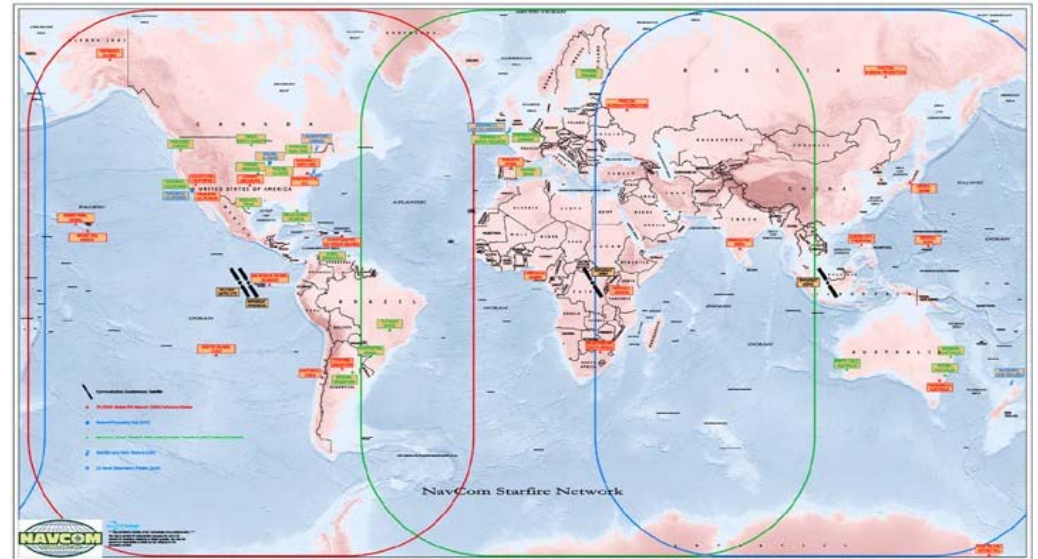


Communication Relay Systems



true global reach:

- open Internet
- 3 Inmarsat satellites with global coverage up to latitude $\pm 75^\circ$ (operated by Navcom, et al.)
- Iridium telephone modems provide internet access globally (including the polar regions)
- future TDRSS broadcast (S-band)

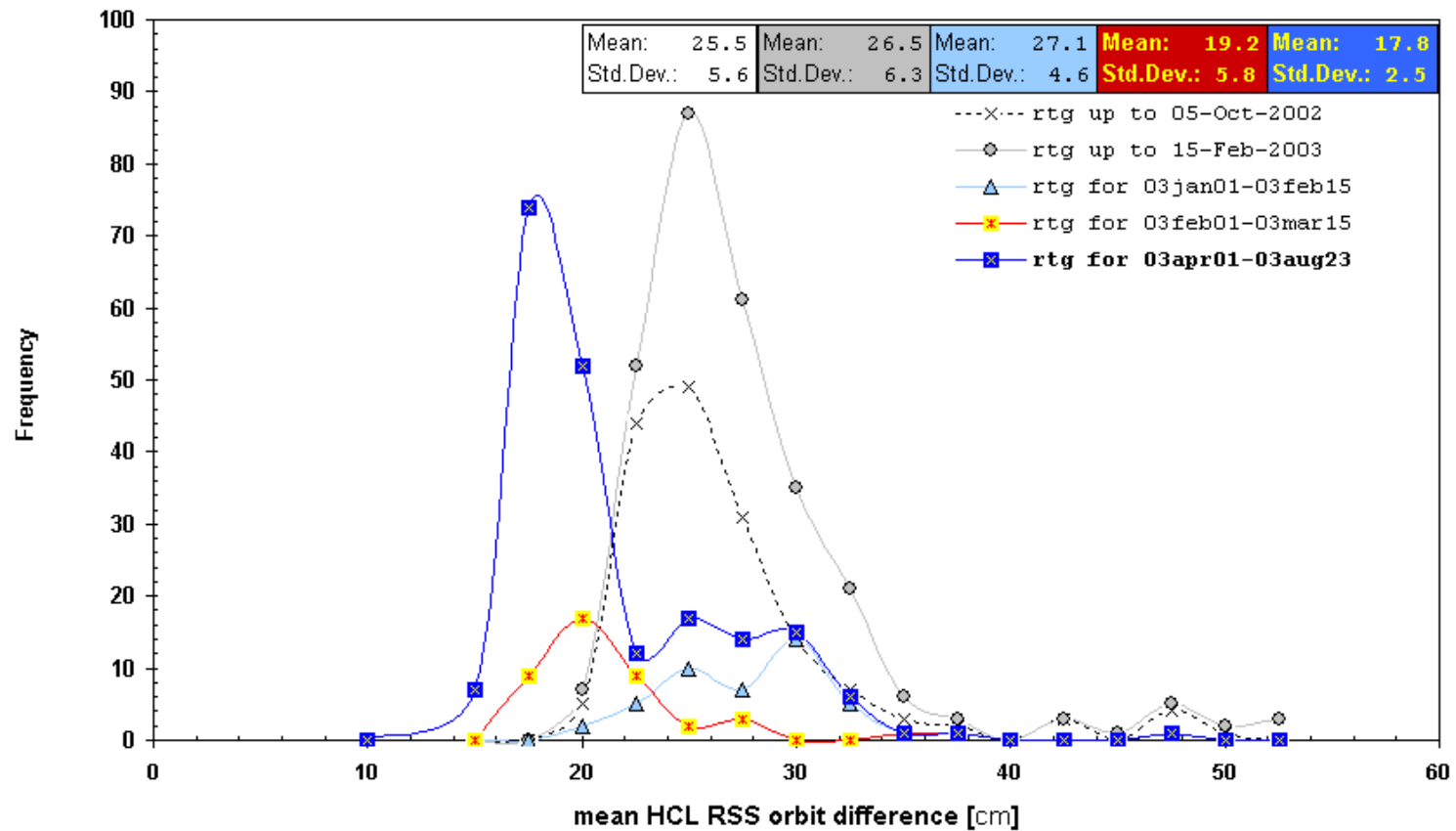




RTG HCL Orbit Differences to FLINN Orbits

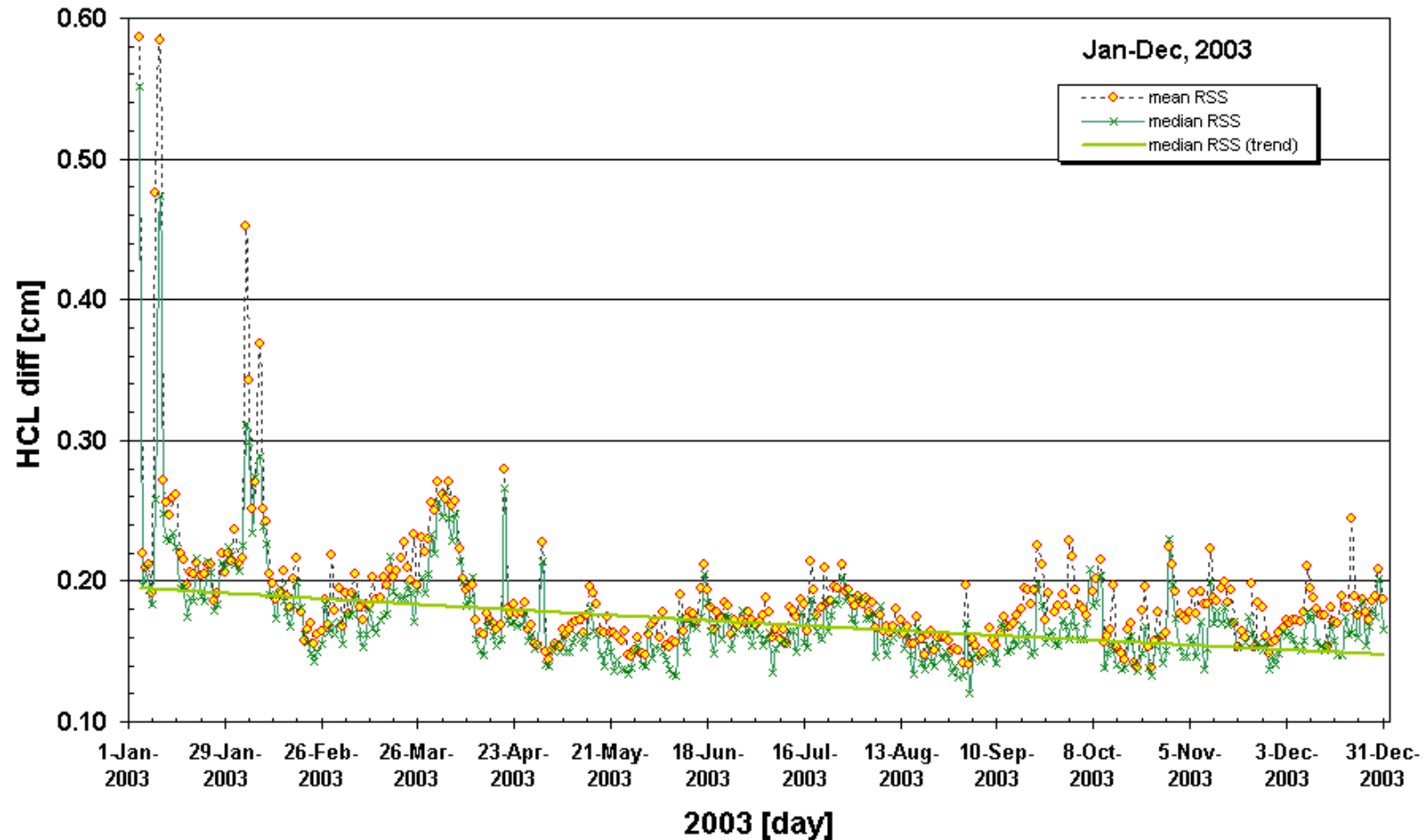
mean RSS per day

[01-APR-2002 to 23-AUG-2003]





JPL RTG vs FLINN orbit diff:
daily mean, median RSS of HCL differences for all SVN

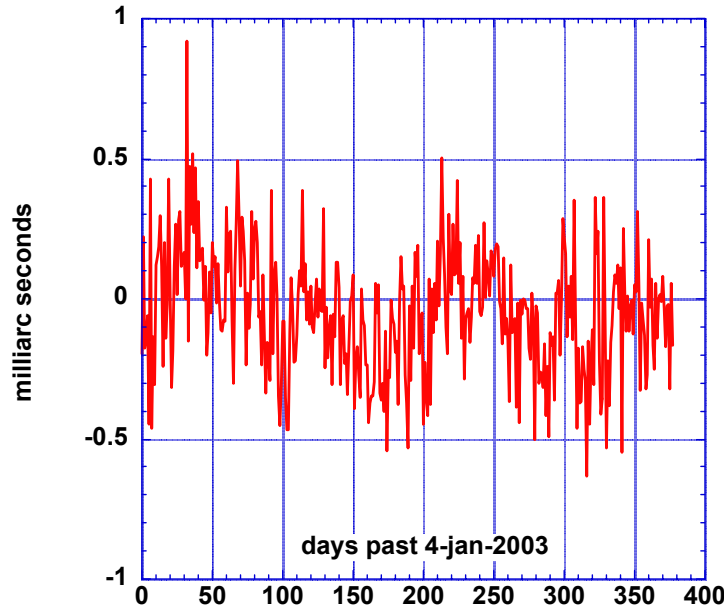




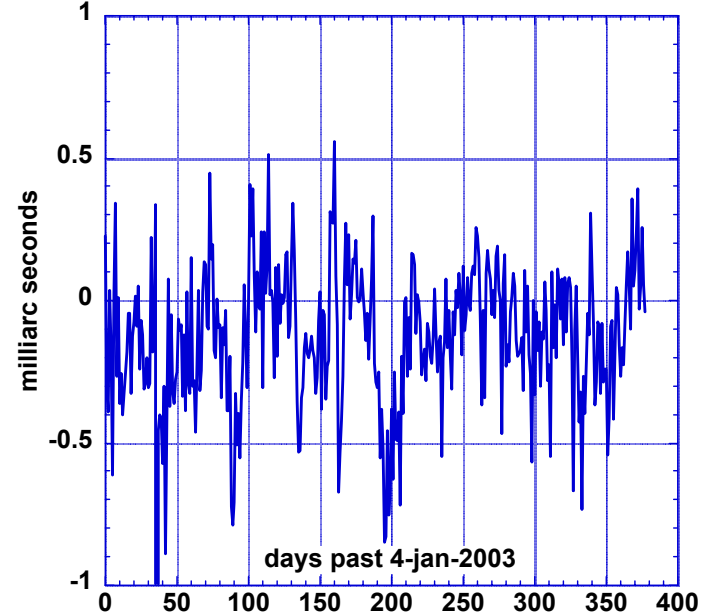
GDGPS Real-Time UTPM Estimates



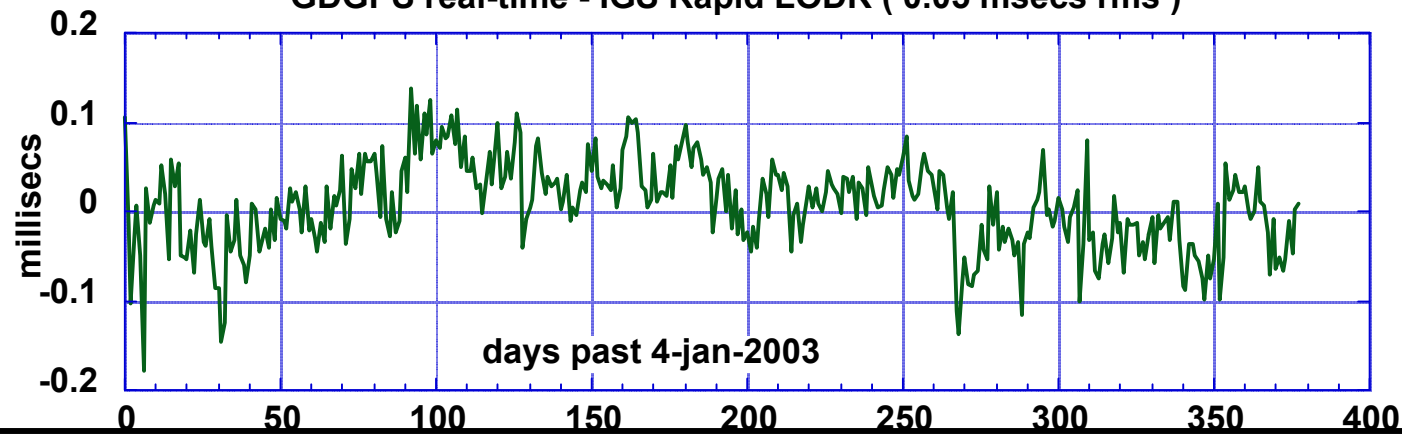
GDGPS real-time - IGS Rapid ypole (0.23 mas rms)



GDGPS real-time - IGS Rapid xpole (0.28 mas rms)



GDGPS real-time - IGS Rapid LODR (0.05 msec rms)

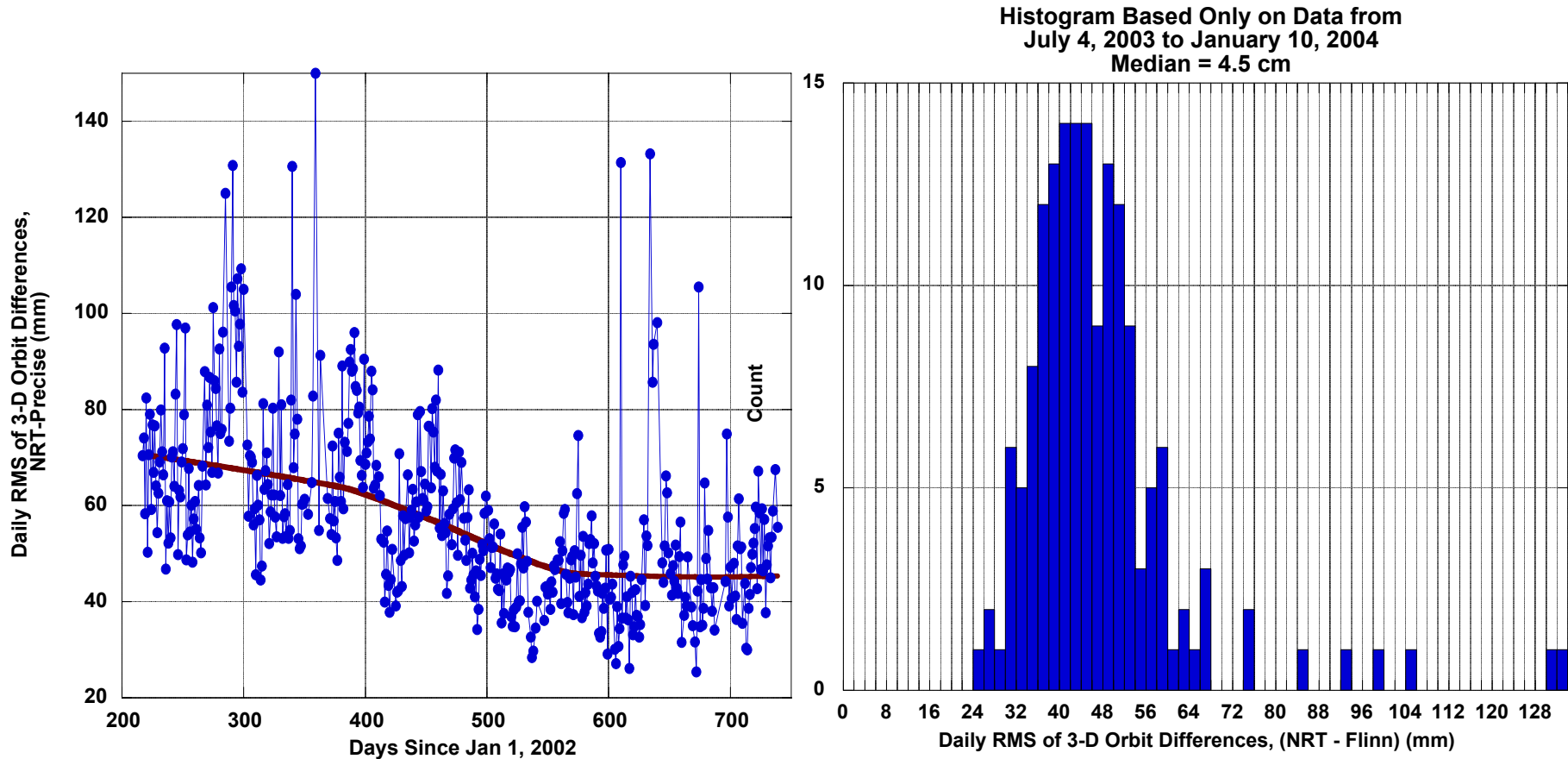




Orbit Determination with GDGPS Products

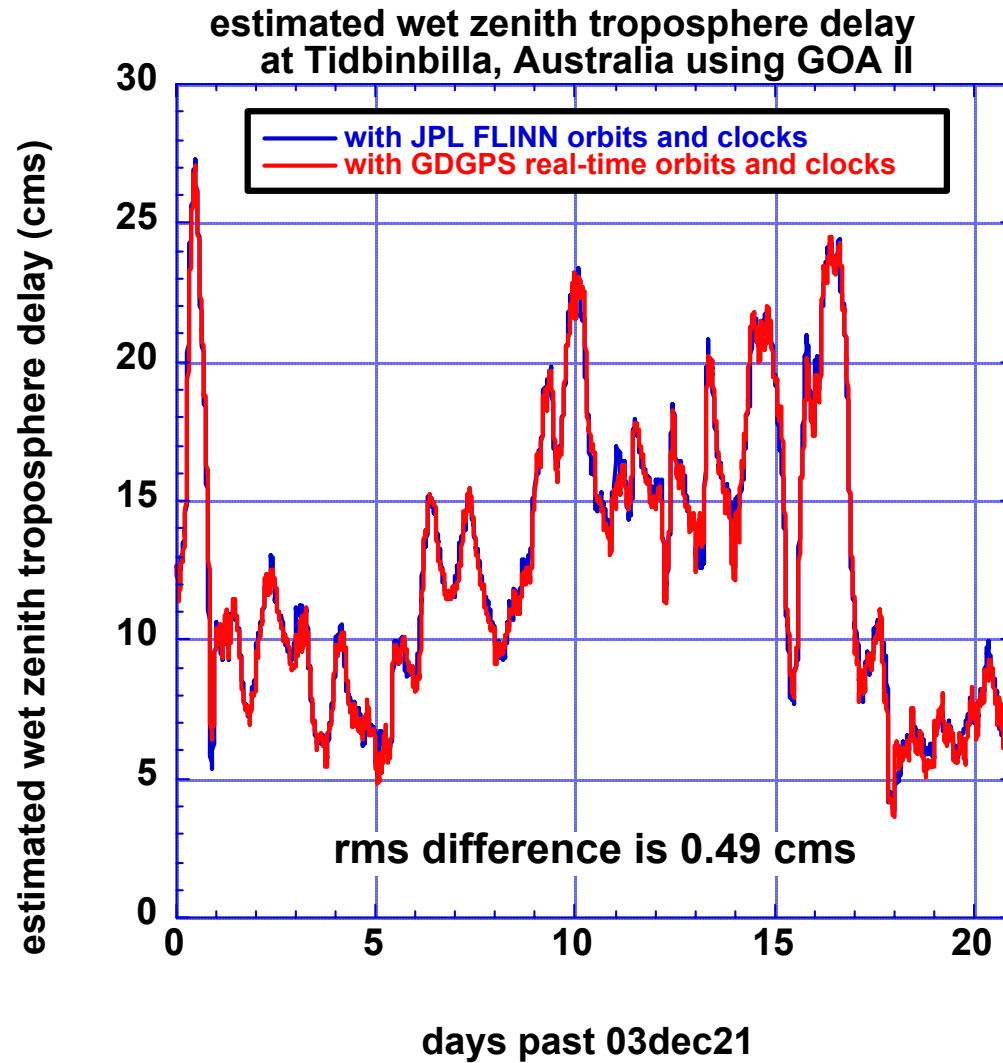


3-D Differences Between NRT and Precise (Flinn) GPS-based Jason-1 Orbits





Troposphere with GDGPS Products



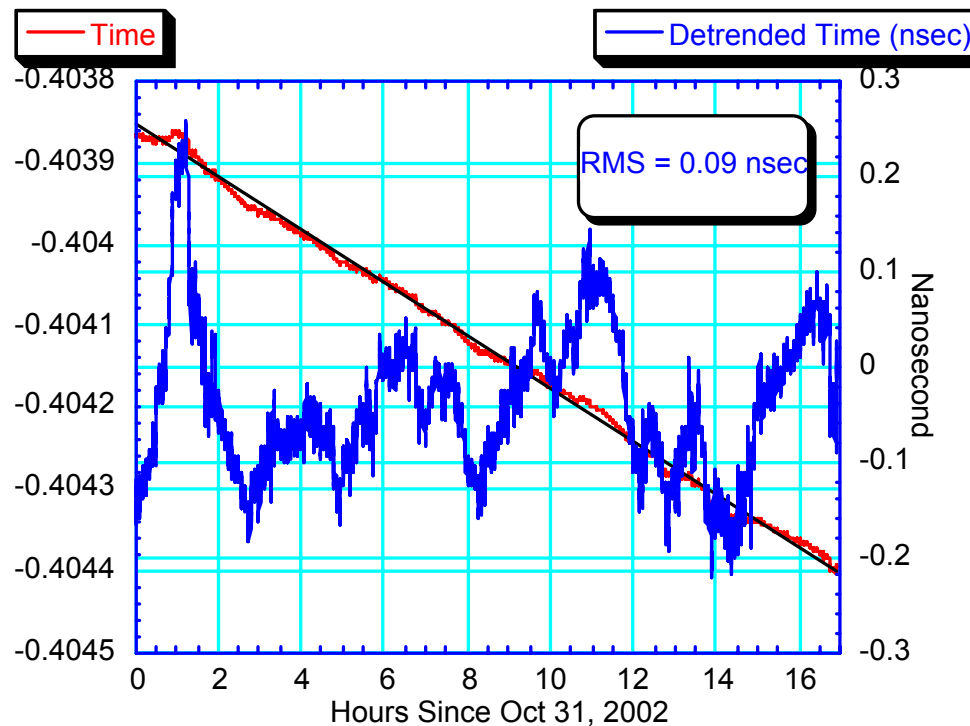


Time Transfer Capabilities



Real-Time time transfer accuracy is consistent with that of positioning:
nanosec level for dynamic platforms; 0.1 nanosec level for static platforms

Time Transfer from USNO to JPL Maser
Position held fixed



An order of magnitude improvement compared to unaided GPS



Centralized vs. Distributed



- **Centralized architecture approach**
 - + **Ease in providing data to end-users in common format**
 - **Data (re)transmission provided by central authority**
 - **Single implemented architecture is not a robust approach**
 - **Single-path nature of central relay does not provide robustness**
 - **And a mesh of relays provides no more redundancy than obtaining the data from a distributive architecture**
 - **End-users of real-time data stream are unknown**
- **Distributive architecture approach**
 - + **Direct access to accumulating organizations**
 - **They are closer to the data**
 - **Likely to have provided multiple access points**
 - + **RTWG has proposed a common data format and method for universal access of available streams**
 - + **Precludes need to relay data through IGS centers**
 - **Avoids potential of data in infinite loop**
 - + **Distributes cognizant knowledge**



Contribution to the IGS Prototype



JPL does not support

- centralized architecture
- redistribution of JPL data through relay

JPL supplies IGS formatted data available from 3 network sources

- supports both UDP and TCP clients
- provides 5 data streams from 3 continents
Goldstone CA, Madrid Spain, Tidbinbilla Australia
AMC1 (Colorado Springs), DLF3 (Delft University)

JPL supports

- open environment for technology development
- data exchange among IGS members
- distributive architecture



Summary



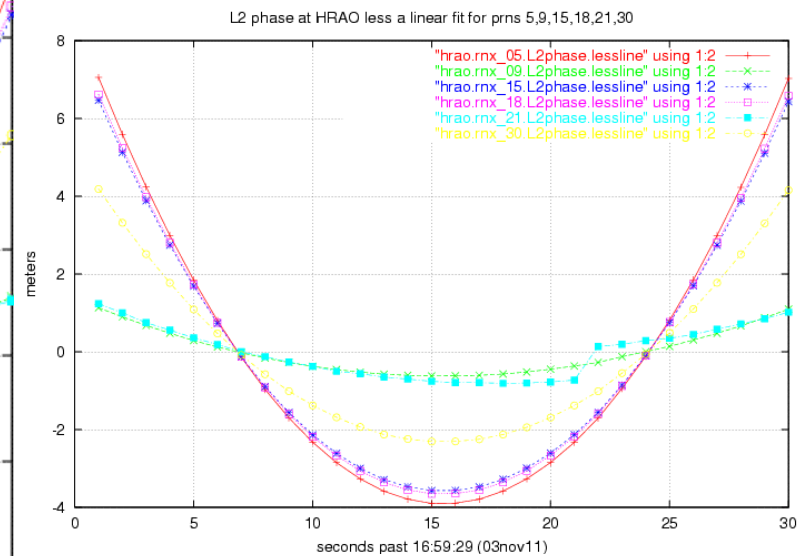
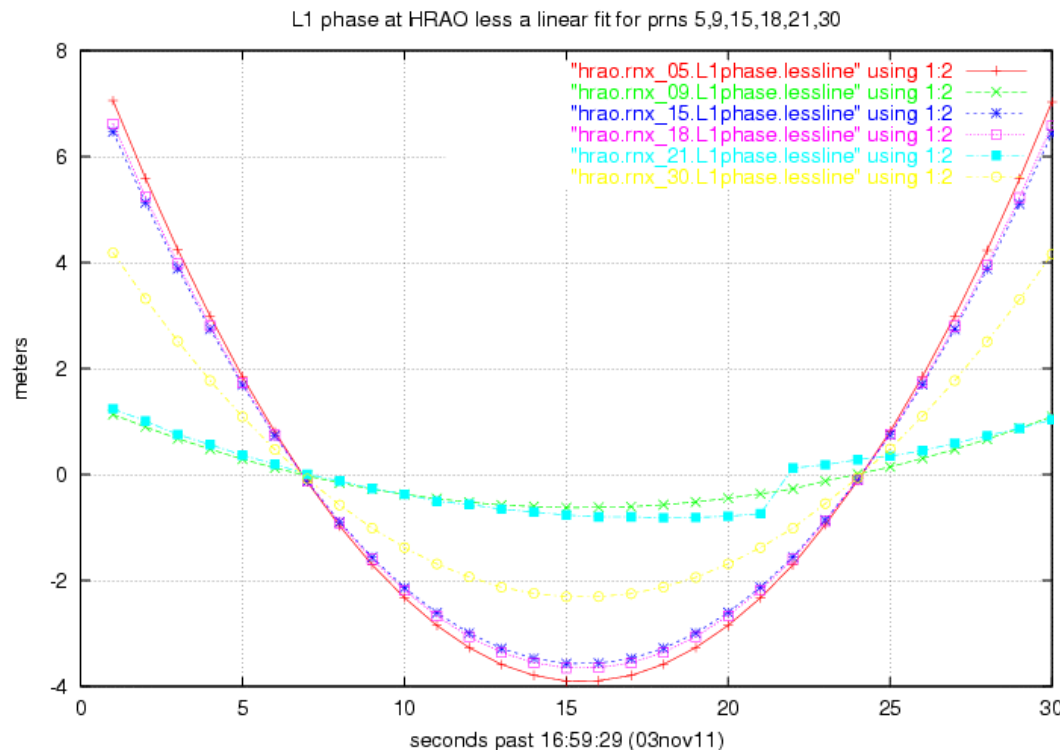
- **some lessons learned**
 - Data must be robustly edited in-situ
 - Monitor, monitor, monitor
 - Expect the unexpected
- **GDGPS has evolved into an operational, highly reliable service since our first claims of 10/20 cms in Y2000**
 - Combined NASA and commercial resources have allowed us to remain economically viable
- **more to do**
 - Data authentication for GPS monitoring
 - Improve orbit models, yaw rates in shadow and noon-turns
 - End-user initial convergence issue
 - Need to reduce long term and short term GPS clock biases



results of one missed cycle slip



- 80 cm jump in PRN21 clock 03nov11 16:59:51
- 9 out of 10 stations reported innovations failures in the filter, only HRAO data passed.





Data editing is difficult and unreliable without data continuity



QuickTime™ and a
TIFF (Uncompressed) decompressor
are needed to see this picture.



Acknowledgement



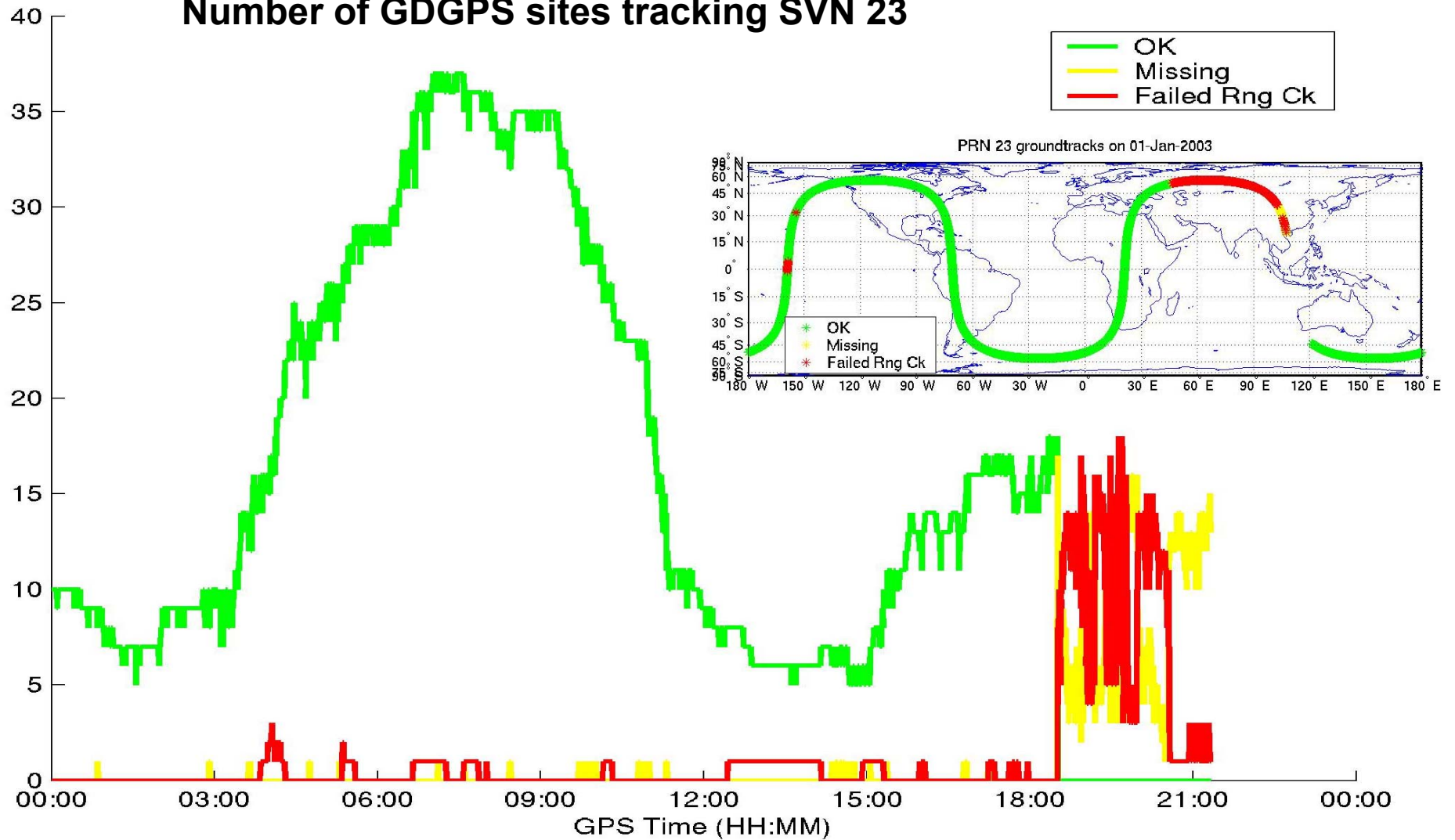
The work described in this paper was carried out by the Jet Propulsion Laboratory, California Institute of Technology, under contract with the National Aeronautics and Space Administration



GDGPS Integrity Monitoring

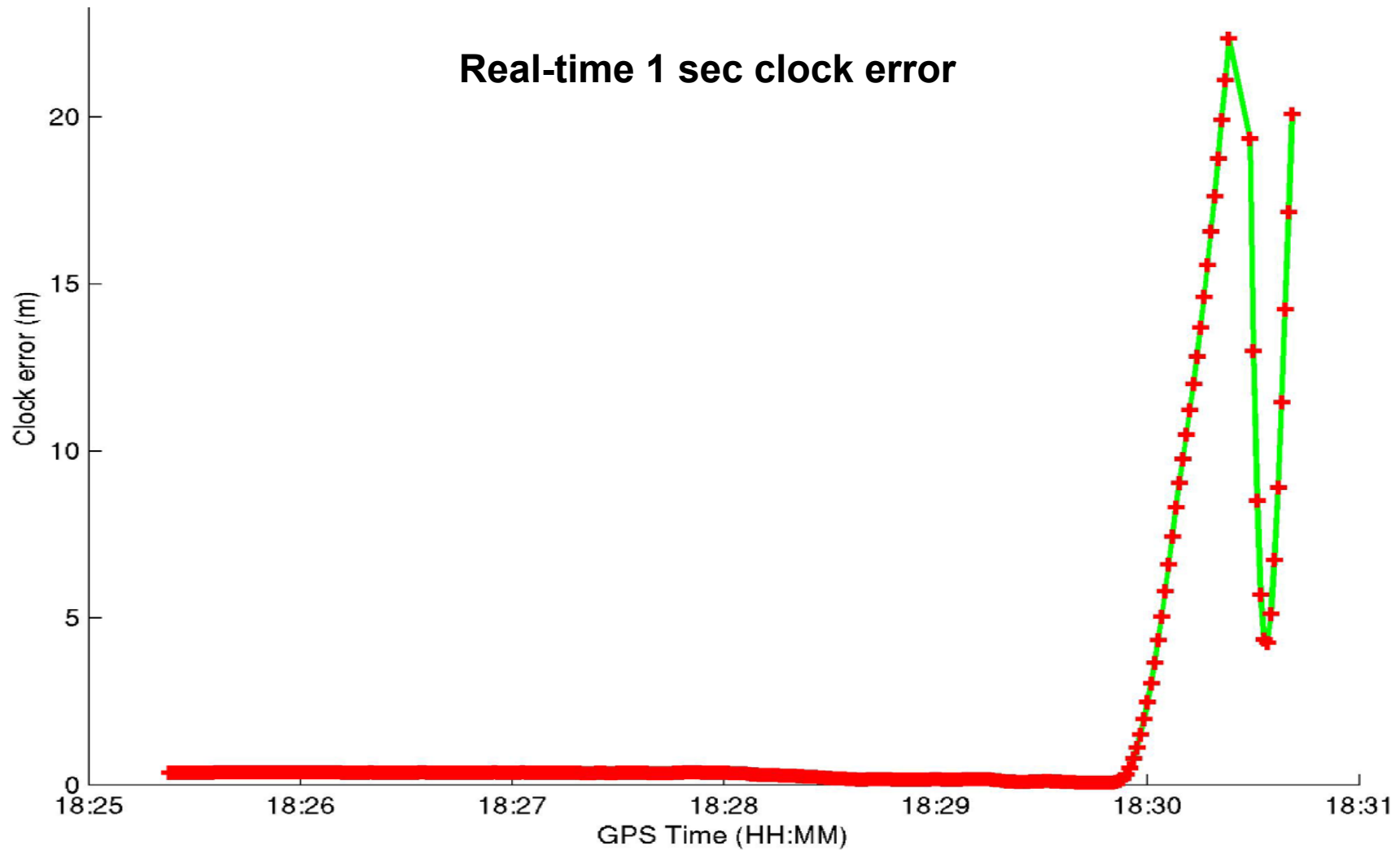


Number of GDGPS sites tracking SVN 23





SVN 23 on January 1 2004 (cont)





Unique Processing Techniques



- **two-stage filter implementation**
 - lag filter applies the correctors optimally to the data.
 - real-time filter services the data using the covariance and estimates from the lag filter.
 - NCT 0.06 to 0.08 seconds latency
 - Ashtech 0.4 secs. latency

